



Ship and Pollution detection via SAR monitoring Synergies between R&D and service activities

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First BreTel Workshop
May 31 - June 1st 2012
Palais du Grand Large, Saint-Malo, FRANCE





Purpose of this presentation



- Presentation of the activities of CLS in the field of vessel and pollution detection with SAR
 - Infrastructure and services
- Complementarities between services and R&D activities
 - Perspectives and R&D activities
- Presentation of the activities of Telecom
 Bretagne in the field of earth observation
 - R&D activities





Plan



- The VIGISAT infrastructure
- Example of services operated by CLS
- Synergies between services and R&D activities
- Open issues and progress in vessel and pollution detection
 - R&D activities of both CLS & Telecom Bretagne







The VIGISAT infrastructure

CLS: THE VIGISAT INFRASTRUCTURE

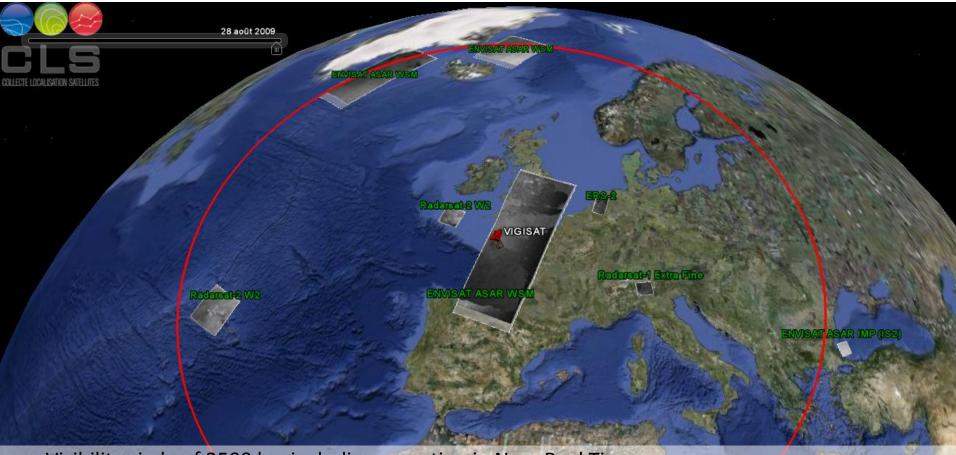




Visibility circle of VIGISAT





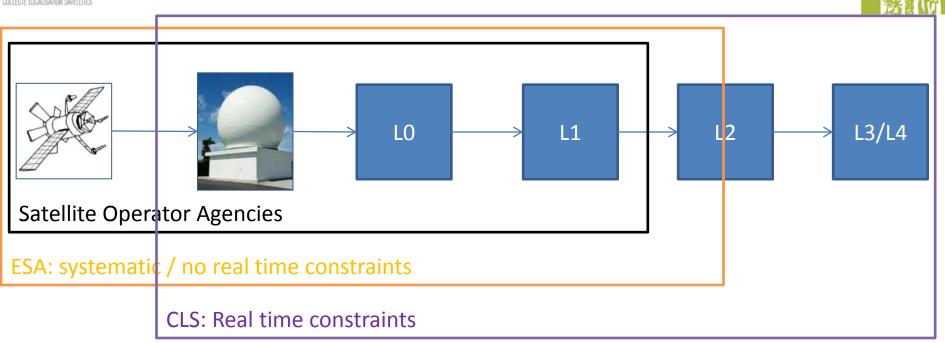


- Visibility circle of 2500 km including reception in Near Real Time :
 - East Greenland, Iceland, Baltic Sea, Western Black Sea
 - Azores, Canarias, North Africa, Central and Western Mediterranean Sea
- Satellite missions received:
 - RADARSAT-1 & 2
 - Formerly Envisat & ERS-2



Near Real Time Data production





Définitions:

- LO: Raw data.
- L1: Geolocated data with the nominal spatial resolution of the instrument.
- L2: Geophysical Parameters derived from the L1 data. Spatial resolution is often degraded in comparison to L0 data.
- L3: Geophysical parameters that have been spatially or/and temporally resampled. Those regridded products can be a composite of several products from the same sensor.
- L4 : Geophysical products combined with other data (Satellite, mode, in-situ)





Example of services operated by CLS

SERVICES OPERATED BY CLS

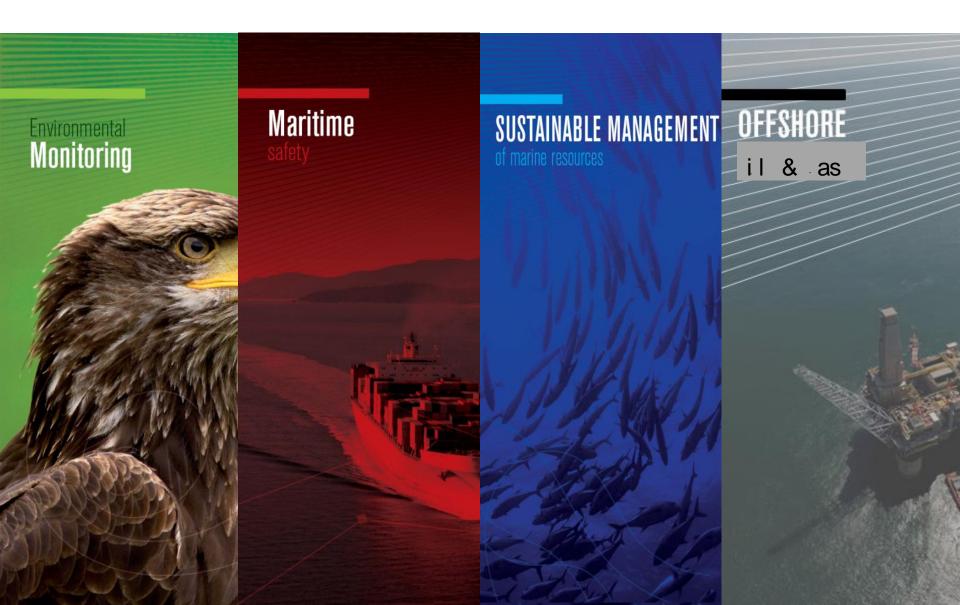




CLS is active in following sectors









Surveillance of marine oil pollutions







Users:

IMO, EMSA, Customs, Maritime Security Agencies, Coastguards, Maritime Affairs, Offshore companies, etc.

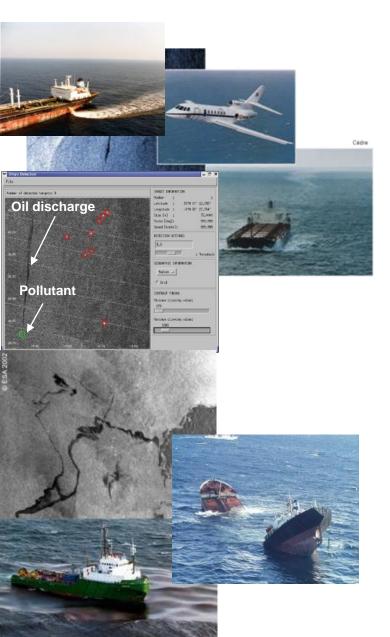




Two types of oil spill scenario Surveillance of marine oil pollutions







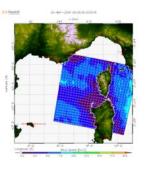
- Illicit oil discharges caused by ships enroute observed by:
 - Aerial surveillance
 - Near-real time satellite surveillance (e.g. CleanSeaNet EMSA service)

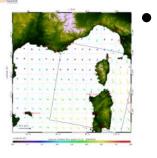
- Accidental pollutions further need:
 - Continuous surveillance and in-situ drifters
 - Risk assessment of onshore drift with meteo-oceanic services



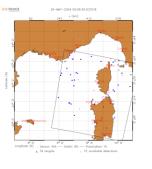
Strategy to reduce the False Alarm Rate Surveillance of marine oil pollutions





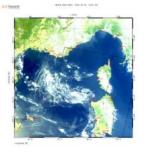


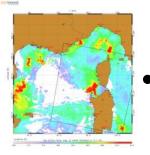
- Use SAR-derived wind information to assess the feasibility of oil spill detection on SAR images
 - -2-3 < |V| < 12-15 m/s in C-band





Couple SAR with AIS/VMS/LRIT information to support the identification of polluting ships





Use ancillary information to help in understanding the origin of ambiguous slicks on SAR images

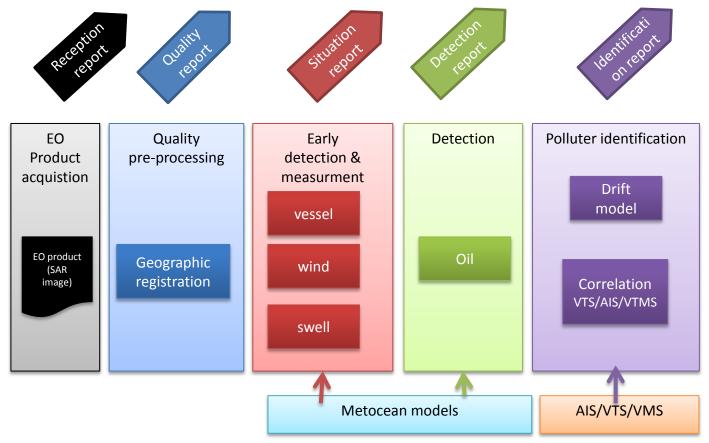




Pollution Operational Service







CLS involved in all those activities:

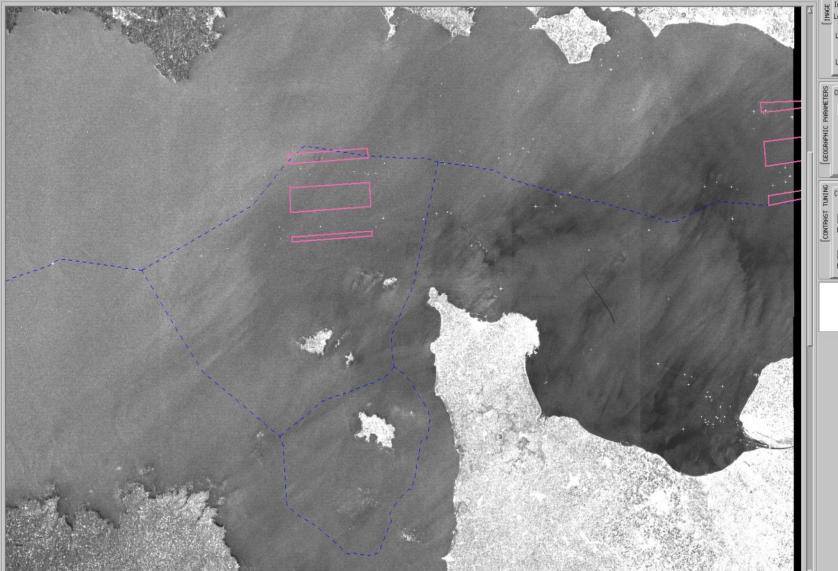
- R&D: define, improve specific sub processing (vessel detection, oil detection...)
- Integration: integrate all processing into one self consistent service chain
- Operational services : operate this kind of chain with real time constraints

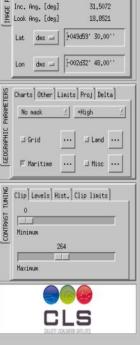


- 6 X SARTool: The SAR Way to Heaven Help File Visualization Full Resolution Applications Ancillary Mouse Mode | Cursor | Data | Quicklook | Sensor | | Pos (X,Y) (973, 1729) PLATFORM: ASAR ENVISAT ACQUISITION UTC TIME: 18-MAY-2009 21:52:58,2 (973, 1729)



ID: ASA_WSM_1PNPDE20090518_215215_000000912079_00101_37730_2065





∉ Value



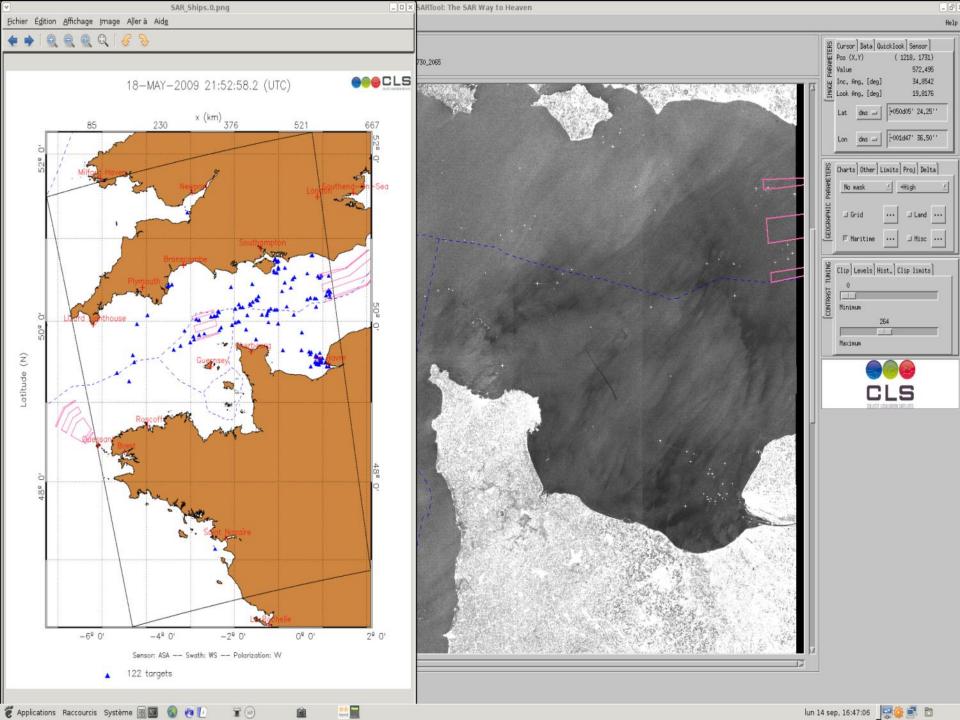




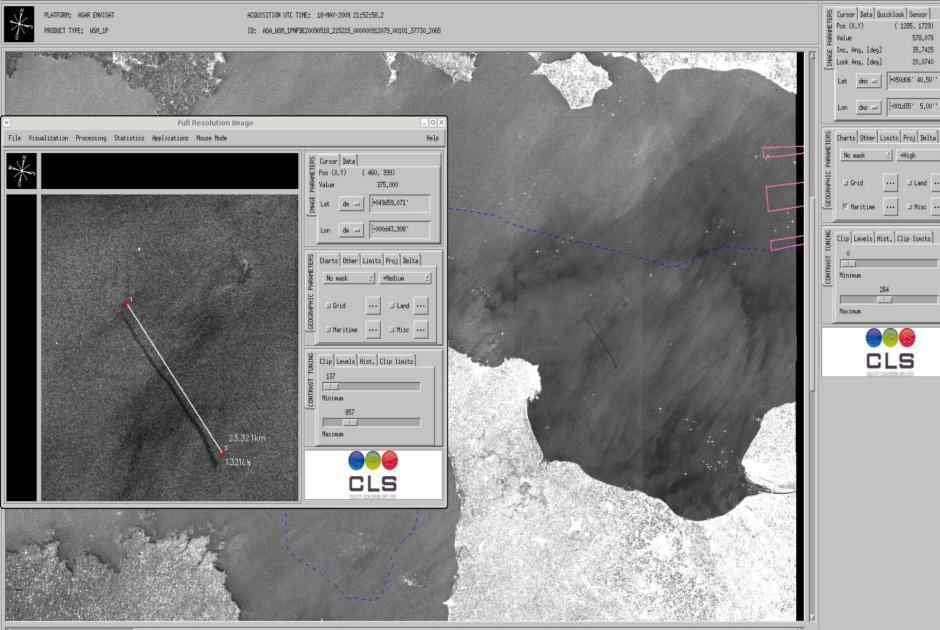








- 6 SARTool: The SAR Way to Heaven Help File Visualization Full Resolution Applications Ancillary Mouse Mode





(1285, 1729)

dns = [+050d06' 40,50'' dns = | -001d35' 5.00''

578,078

35,7425

20,0740

☐ Land ···

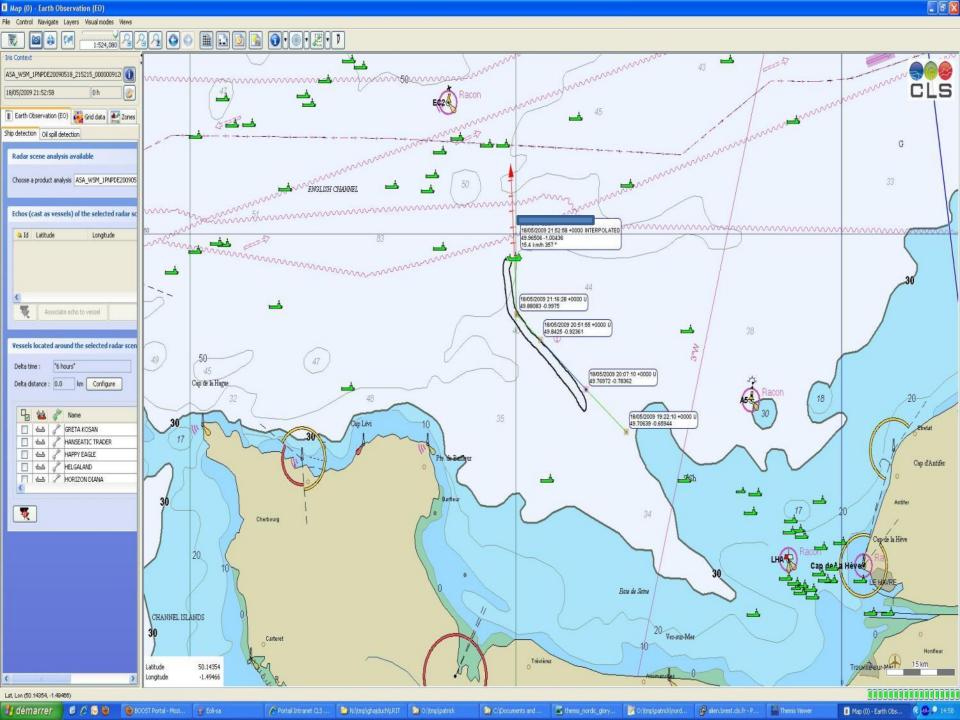
⊿ Misc ···















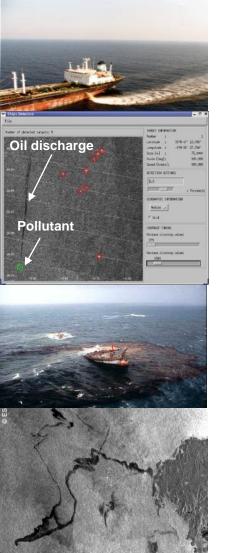
Pollution detection: The CleanSeaNet service

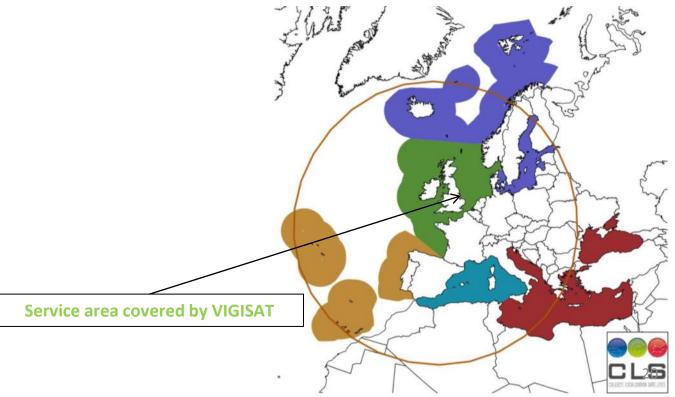




Clean Sea Net / European Maritime Safety Agency/

- A <u>near real-time</u> detection service of <u>oil spills and ships</u> at sea using SAR imagery
 - Delivered by EMSA (Lisbon) since 17 April 2007
 - To apply the European directive 2005/35/EC :
 - Detect from space oil spills at sea
 - To identify the source of pollution







Other services



- Monitoring of illegal or unreported fishing:
 - Fishing licenses
 - Fish farms
- Border surveillance
- Marine Traffic surveillance
- Environmental monitoring
 - Wind
 - Swell
 - Currents
- etc







Synergies between services and R&D activities

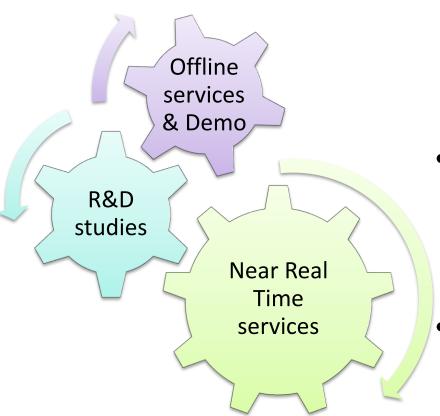
CLS: FROM R&D ACTIVITIES TO SERVICES... AND BACK





Coordination of R&D and Services

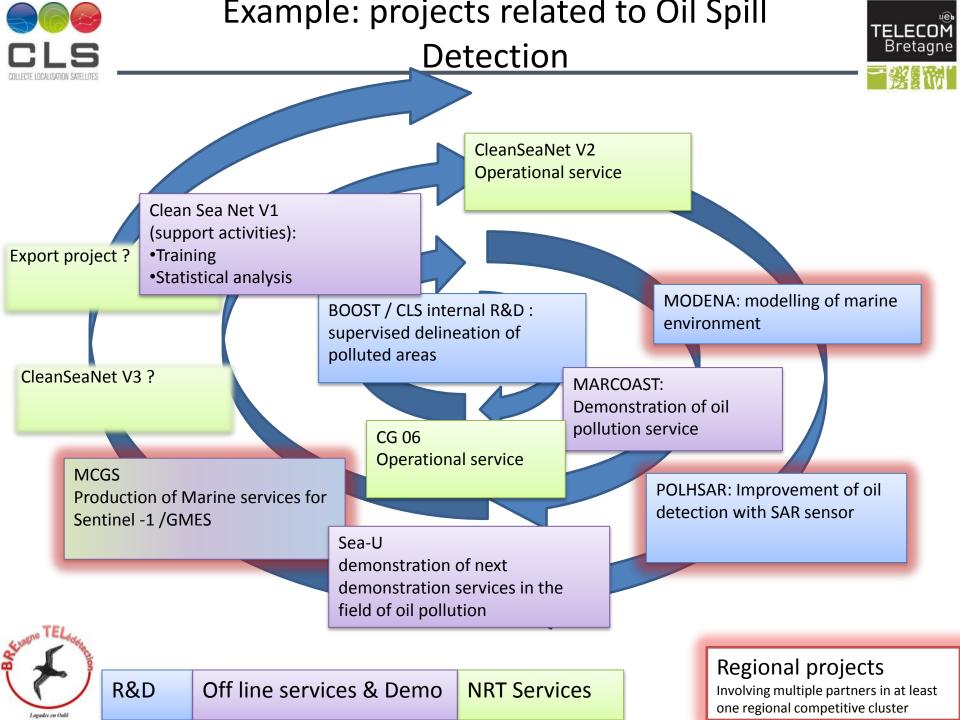




R&D studies:

- Preliminaries studies
- Improvements of processing
- Offline services
 - Statistical analysis
 - Quality & performance assessment
- Real time services
 - Operational delivery of products and analysis







MODENA: Modelling of Marine Environment



- Founded by:
 - FUI, Conseil Régional Bretagne, City of Brest, ANR
- Multi partners:
 - ARTAL Technologies, Telecom Bretagne, Ifremer, ENSTA Bretagne, IETR, CLS, Marée...
- Purpose of CLS contribution
 - Modelling of medium resolution backscattering of the sea surface in X and C band
 - Provision of satellite SAR data for the validation of the MODENA simulator
 - Validation of the calibration of the MODENA simulator
- Benefits for oil spill detection
 - Better knowledge of backscattering of clean sea





POLHSAR: Improvement of pollution detection with SAR



- Founded by:
 - ANR
- Multi partners:
 - Thales Systèmes Aéroportés, IETR (IREENA)
- Purpose of CLS contribution
 - Modelling of medium resolution backscattering of the sea surface in X band from new CosmoSkymed Data
 - Characterisation of polluted area
 - Characterisation of instrumental artefacts
 - Extension of pollution detection at high and low incidence angle and in X Band
 - Provision of satellite SAR data for validation of backscattering model of polluted area
- Benefits for oil spill detection
 - Oil spill detection at low/high incidence angle and in X-band





MCGS: Environmental monitoring



- Founded by:
 - FUI
- Multi Partners
 - ACRI, CLS, GIS Bretel (Telecom Bretagne, Ifremer)
- MCGS: Marine Collaborative Ground Segment
 - Complement of Core Ground Segment of ESA for the GMES / Sentinel program
 - European coverage
 - Real time service & reprocessing services
 - High resolution measurement of wind, wave, current
 - Help for prediction of marine situation







Open issues and progress in vessel and pollution detection

ISSUES AND PROGRESS OF SHIP AND VESSEL DETECTION





Vessel detection: extension of operational requirements



- Pre processings
 - Automatic correction of mis registration
- Better detection
 - Detection of smaller vessels
 - In higher resolution products
- Better characterisation of detected vessels
 - Better measurement of length and type
 - Better Iceberg detection
- Detection in difficult scenarios
 - Detection of vessel in ice pack
- Improvement in computation time
 - Preparation for Sentinel 1 : multiplication by 300 of the volume of data
- Better exploitation of detected vessel
 - Automatic correlation of detected vessels and AIS





Preprocessing: Automatic geographic registration of SAR image



Mutual Information Metric Mattes et al. Implementation et Transformation Affine





Objective: Automatic and Real Time registration of shifted data

Center X = 551.5

Center Y = 1025.5

Translation X = -1.45075

Translation Y = -38.4239

Iterations = 43

Metric value = -0.250858

Scale 1 = 1.00121

Scale 2 = 0.999051

Angle (degrees) = -0.0523533



Characterisation: better length estimation



- Improvement in length estimation
- Standard technique:
 - Measurement of the shape of the detected echo
- Implemented technique:
 - Measurement of the shape
 - Measurement of the radar cross section of the echo and estimation of the corresponding size
 - Fusion of both measurements (fuzy logic)





Characterisation: Attempts of Vessel recognition in RS2 Multi Look Fine data





03: NORGAS TRADER

Pavillon : Singapour

Type : Transport de gaz liquéfié

Dimensions : 119 m x 18 m

Dimensions SAR: auto 145 m, manuelle 135 m $\,$

Code MMSI : 563662000

04: GRAND SAPPHIRE

Pavillon : Panama

Type : Transport de véhicule

Dimensions : 199 m x 32 m

Dimensions SAR: auto 402 m, manuelle 206 m

Code MMSI : 372516000

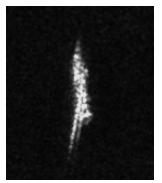
05: HARMEN OLDENDORFF

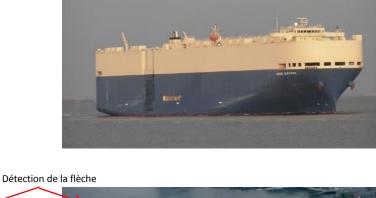
Pavillon : Liberia
Type : Minéralier
Dimensions : 225 m x 32 m

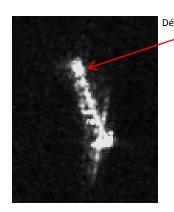
Dimensions SAR: auto 348 m, manuelle 221 m

Code MMSI : 636090932













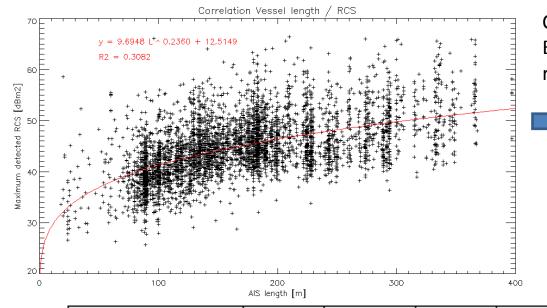


Characteristion: RCS model of vessels





Modelling of vessel backscattering



Coupling between SAR & AIS Empirical modelling of vessel RCS with respect to it's size and incidence angle



$$\sigma = g(L, \theta)$$



$$L = h(\sigma, \theta)$$

Mode	a_0	a_1	a_2	a_3
ASA WSM VV	0.7240	32.7967	0.1131	0.1499
ASA WSM HH	0.5557	32.7650	0.1036	0.1663
ASA IMM HH	0.6216	43.5251	0.1086	0.6216
CSK HR HH	0.9327	38.1860	0.2005	0.0977
RS2 SCNA HH	0.9099	41.2843	0.3883	0.0956

$$L = \frac{\sigma}{a_0(a_1 - a_2\theta)}^{\frac{1}{a_2}}$$

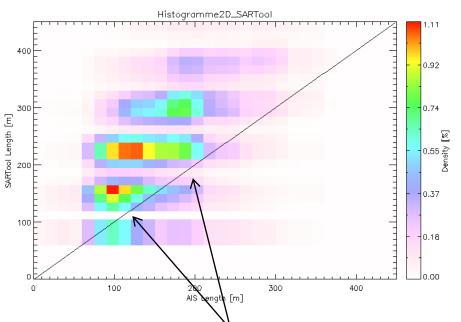




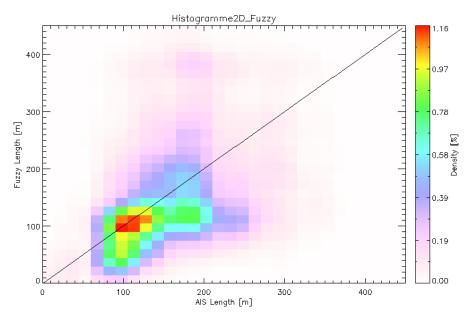
Results of fuzy logic size estimation



Geometric criteria only



Fused Geometric & Radiometric



- geometric approach with step effect: related to the geometric estimation + pixel spacing.
- •Improvement of length estimation (better fit of the data, no step effect)
- Effective fusion for medium resolution products



• 6447 vessels for the test, 1930 for the learning of the RCS low and fusion.

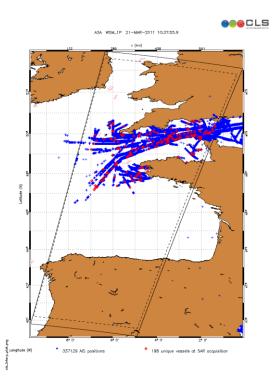


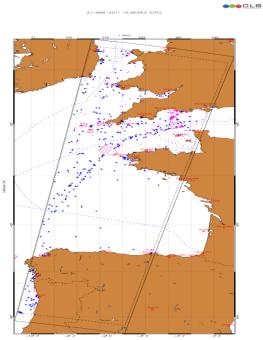
Exploitation: Automatic AIS-SAR coupling: methodology





- Spatial interpolation of AIS positions
 - 2 possibles cases:
 - Several positions known: interpolation (polynomial) with geographical positions
 - Only one position available: interpolation interpolation with speed and route information
- Temporal interpolation
 - Fonction of azimuthal position
- Counter-balancing of azimuthal offset for AIS positions
 - Depending on radial velocity, incidence angle, speed and satellite height
- Automatic coupling: iterative research of minimum AIS-SAR distance





SAR-based detected target with reliable and unreliable



AIS positions within +- 2 hours with

positions at SAR acquisitions

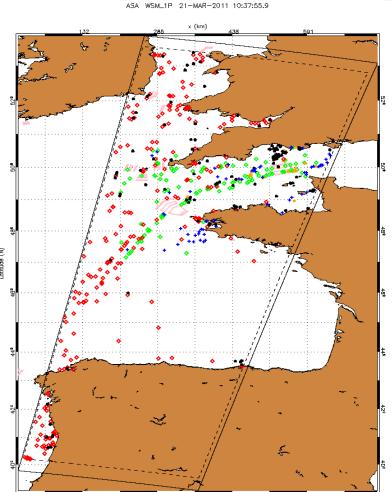


Exploitation: Qualitative assessment of ship detection









SAR targets unmatched with AIS

438 unreliable

238 reliable

AS unmatched

+68 positions

SAR targets matched with AIS

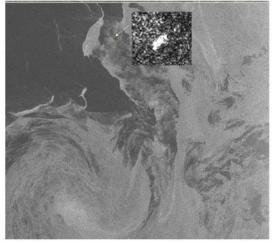
- Color code:
 - Green: reliable SAR targets matched with AIS position
 - Orange: unreliable SAR targets matched with AIS position
 - Red: Reliable SAR targets unmatched with AIS position
 - Black: Unreliable SAR targets unmatched with AIS position
 - Blue: AIS position unmtached
- 2 main issues
 - Many red points: range of AIS reception or false alarms
 - Many blue points: non detection by SAR image
- Perspectives
 - Need for a comprehensive understanding of:
 - AIS data reception for each station: range, angular aspect, sea state/atmosphere dependency...
 - Non detection linked to the SAR image itself



Other Scenarios: Vessel detection in sea-ice







© C Brekke et al. Ship detection in ice infested waters based on dual-polarization SAR imagery, GRSL, vol 8(3) may 2011.

Academic tour

- Poor bibliography
- Use dual pol and low incidence angle
- Based on `classical' statistical tests used for target detection





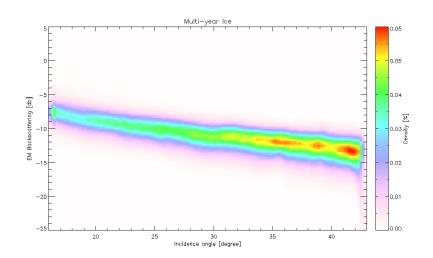
Other scenario: Sea Ice Characterisation

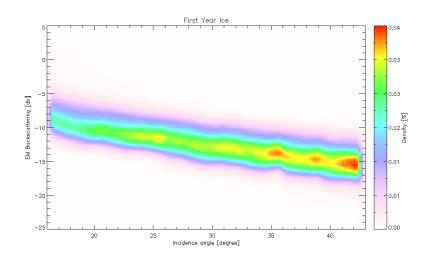




NRCS vs incidence angle for Multi Year Ice

NRCS vs incidence angle for First Year Ice









Oil detection: extension of operational requirements



- Better detection
 - Semi-automated oil spill detection
- Better characterisation of detected pollution
 - Automated coupling of polluted area and detected vessels based on drift model

etc





Conclusion



- Synergies of R&D / off line services / near real time services
- Mutual interest on those subjects from private companies, academics...
- Links between those actors through:
 - GIS
 - Regional Clusters
- Large number of research and services topics in vessel detection, oil spill detection and environmental monitoring
 - MCGS
 - Sea-U (FP7) on oil spill detection services
 - DOLPHIN (FP7) on vessel detection services

